## **Adversarial Attacks**

# in the Real World





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## Independent consultant

- Technical competitions
- Algorithms
- Cybersecurity R&D





#### Let's start with the basics.

# What *really* is a neural network?











## What really happens inside?































## What is training?

### Initially, the neural net does not know what to do

- It can approximate any function
- Adjust parameters (weights and biases)
- Learn their correct values through training






















## Repeat many times, over many examples

After enough training steps, the neural network will approximate human evaluation

### Parameter adjustments use the <u>gradient</u>

#### Neural nets must be **continuous** and **differentiable**

### Parameter adjustments use the gradient

### Neural nets must be **continuous** and **differentiable**

We can exploit these properties!

### Neural networks are not "smooth"



~ Ankur Mohan

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# What do these irregularities mean?

# A <u>small perturbation</u> on the input (in a carefully chosen direction)

# can change the output by a lot

### Original







#### Each pixel is changed by 1 bit

### Original







### Panda

### Chair (99.9%)

## Pandas are nice, but let's break something cooler.

# Self-driving cars!

### Disclaimer

For legal and practical reasons, the following attacks will be demonstrated on a simulated environment.

(but they also work on actual cars)



# **Objective:**

Get this sign to be detected as "speed limit 50"

## How do we find the correct perturbation?

### How do we find the correct perturbation?

# Use the gradient!

# **Partial derivative**

 $\partial score$ 

 $\partial pixel_{x,y}$ 

# **Partial derivative**

*∂score* 

how will the **score** change

#### if

 $\partial pixel_{x,y}$ 

this **pixel** changes slightly

# **Partial derivative**

*∂score* 

how will the **score** change

#### if

 $\partial pixel_{x,y}$ 

this **pixel** changes slightly

We can also see it as a <u>correlation</u> coefficient

## **Gradient-based adversarial attacks**

### Change **all** pixels **slightly** in the gradient direction

OR

#### Change **a few** most significant pixels **all the way**

#### **FGSM** Many small changes



Speed limit 50 (99.9%)

#### **JSMA** Few large changes



### Speed limit 50 (99.9%)

## These attacks are not **robust**

#### They are very sensitive to:

- Camera noise
- Object angle
- Lighting
- Background

#### Infected image raw file



Speed limit 50 (99.9%)

#### **Infected image** smartphone photo



Stop (97.6%)

#### **Infected image** original perturbation



Speed limit 50 (99.9%)

### Infected image

same perturbation, different pose



Stop (98.0%)

# 2 conditions needed

- Bit-perfect input
- White-box access to the model

# How do we make a better attack?

# We want a perturbation that is:

- physically applied to the sign
- as stealthy as possible
- robust on a wide range of conditions
- without access to the model gradients



# **Noise resistance** can be achieved by using larger stickers

# Black-box attack

We don't have access to gradients, but we can still get the prediction score

### Try many configurations and keep the best



# Black-box attack

- Not very efficient to do manually
- Need to try millions of combinations
- Not very reproducible
- → Work in a **virtual** attack setup







The same perturbation can now be simulated over many different conditions

Eliminates all external variables

- Noise
- Position/angle
- Lighting and reflections
- Background

## How do we search for good perturbations?

### <u>Bruteforce</u> - try all possible combinations

### Guaranteed to find the optimal solution

...but takes 10<sup>25</sup> years 😱

## How do we search for good perturbations?

### <u>Monte-Carlo</u> - try random perturbations

Good perturbations are rare (~1 in a billion)

Need to be **very lucky**
#### Work <u>step by step</u>



#### Work <u>step by step</u>

# Test many configurations for sticker **1**, keep the best



#### Work <u>step by step</u>

# Test many configurations for sticker **2**, keep the best



#### Work <u>step by step</u>

# Test many configurations for sticker **3**, keep the best



#### Work <u>step by step</u>

etc.



# Small improvement: add an **optimization** step to search locally for the best attack

#### Inspired by mutations in genetic algorithms

#### After adding each sticker, try moving the other ones slightly



#### After adding each sticker, try moving the other ones slightly



#### Attack performance @ 3min per patch



#### Attack performance @ 3min per patch



#### **Demo time!**







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#### ? as stealthy as possible

#### **V** robust on a wide range of conditions

#### without access to the model gradients

## This PoC can be improved. Ideas:

- More stealth
- Black-box++

#### All neural networks are vulnerable to

adversarial attacks, and

**no efficient protections** currently exist.



## Any questions?

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